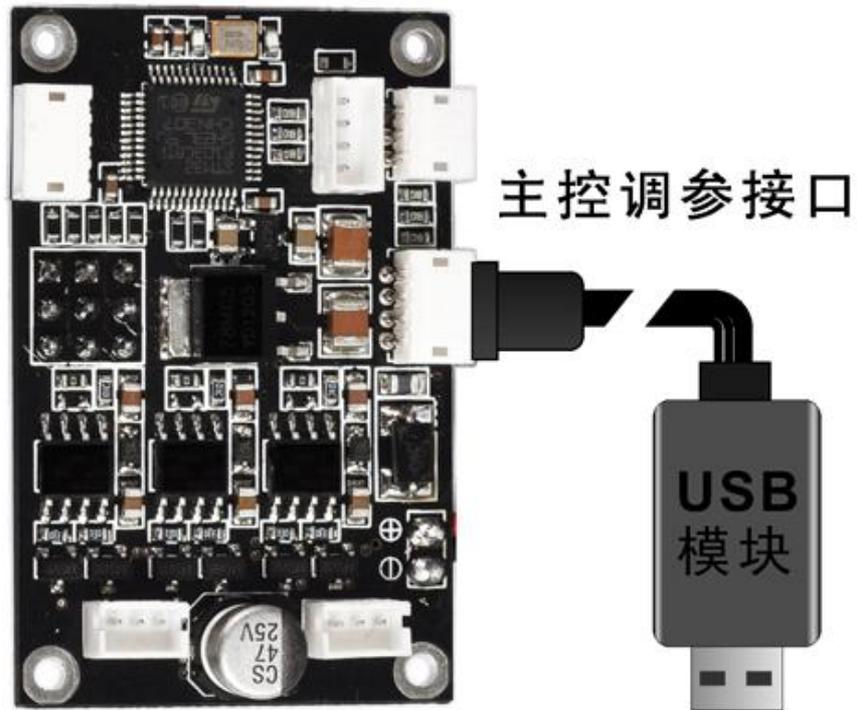


T-2D Brushless Gimbal Additional Remarks 2013-6-28

Controller interface and connection introduction:

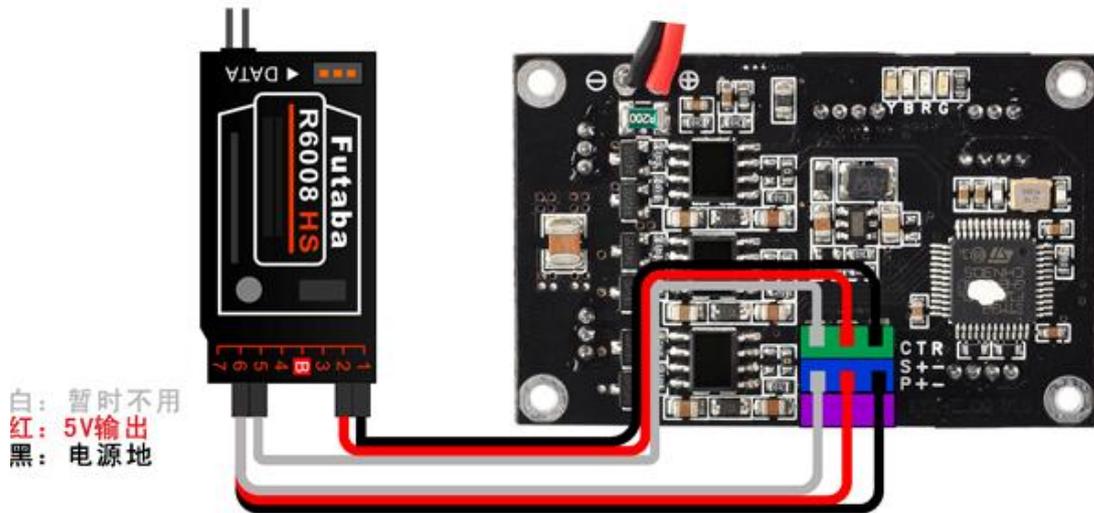
1.Gimbal controller connector: Via USB module connected to the computer. When you use this USB Module at first time , please intall its dirver.



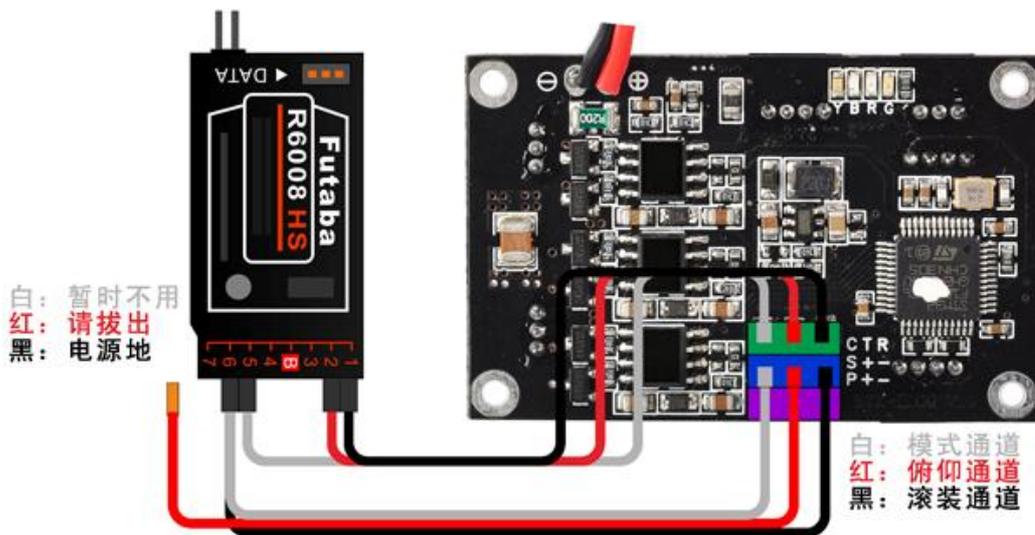
2.Motor driver connector: Via USB module connected to the computer for setting motor parameters.



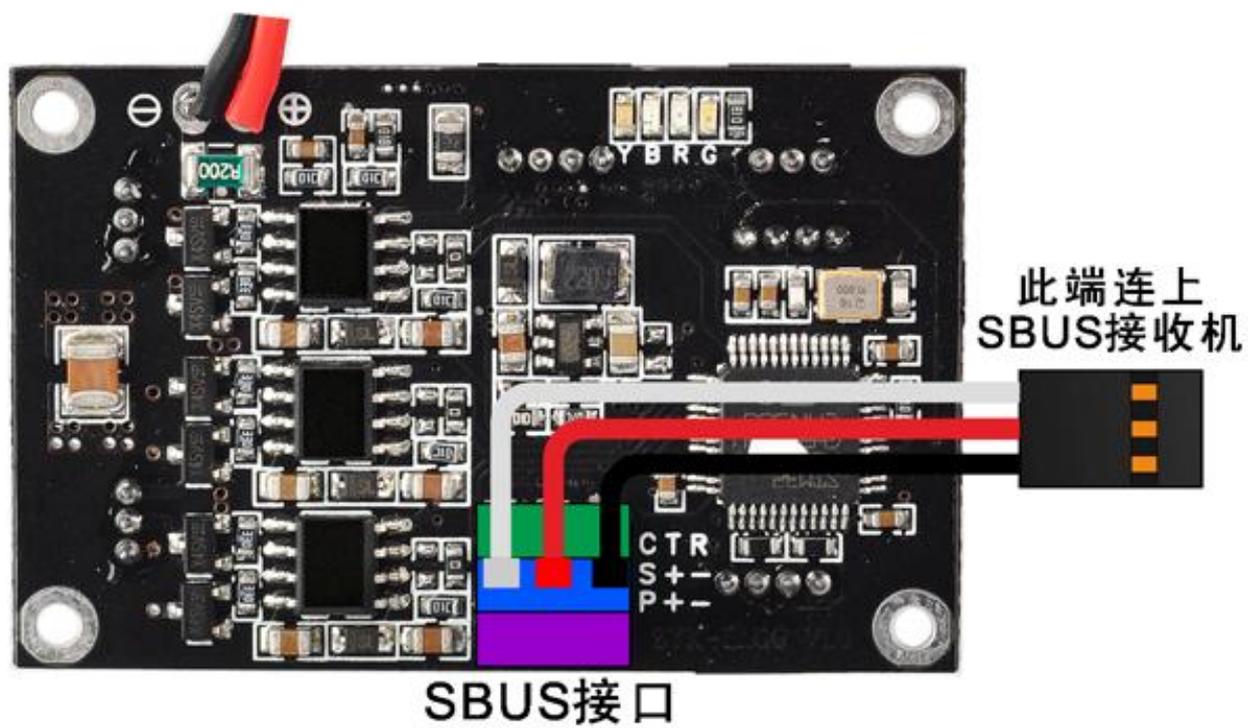
3.Connected with independent conventional receiver: users can select Mode/Tilt/Roll input channel connect to conventional receiver, and make sure power ground connection rightly.



4.Connected with flight controller receiver: users can select Mode/Tilt/Roll input channel connect to conventional receiver, and make sure power ground connection rightly, but do not connect the 5V output wire.



5.SBUS receiver:



6.DSM2/DSMJ/DSMX receiver type:

DSM2-1: Transmitter is DX7 etc. (binding by 6 or 7 channels receiver)

DSM2-2: Transmitter is DX8, DSX9 etc. (binding by 6 or 7 channels receiver)

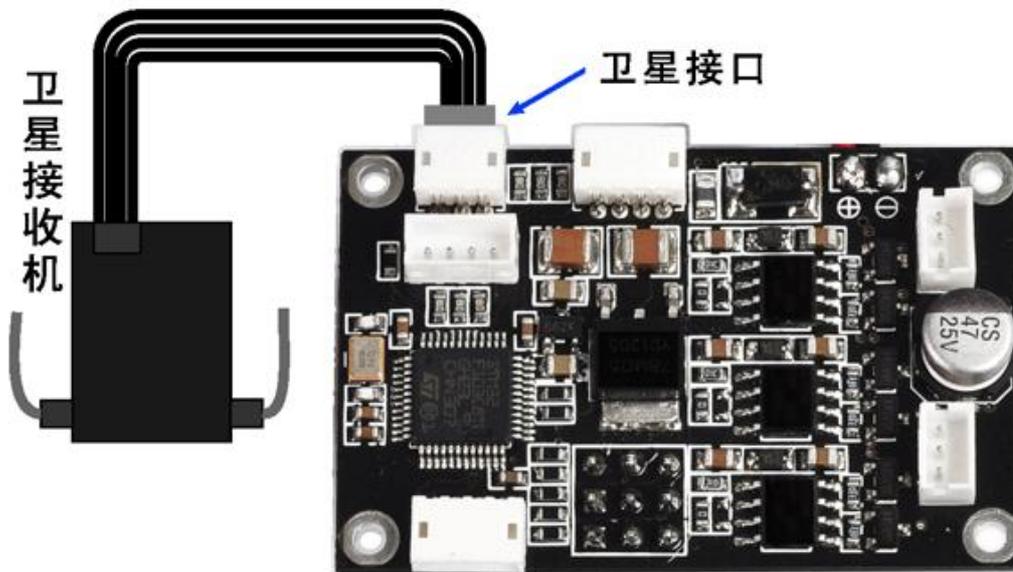
DSM2-3: Transmitter is DX8, DSX9 etc. (binding by 9 channels receiver)

DSM2-4: Transmitter is DM8, DM9 module. (binding by 6 or 7 channels receiver)

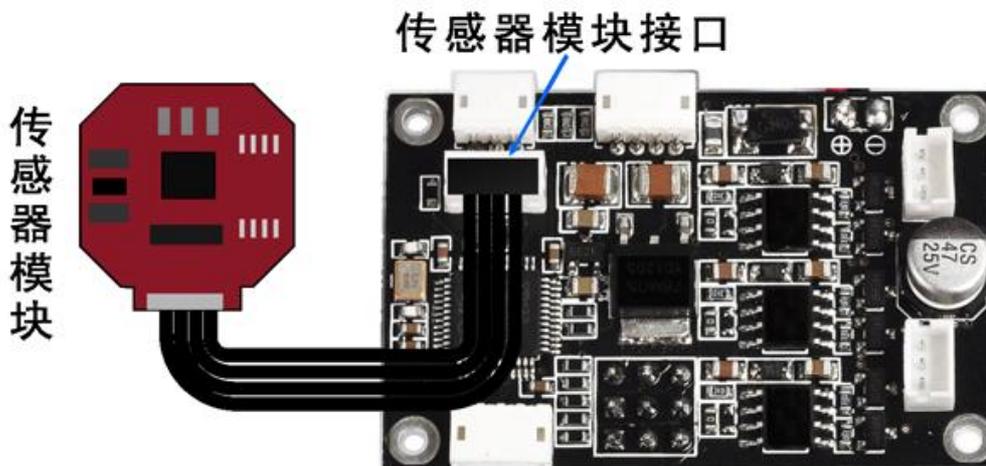
DSMJ: Transmitter is DSMJ format. (Binding by matched receiver)

DSMX-1: Transmitter is DX 8 etc. (11ms mode, binding by matched receiver)

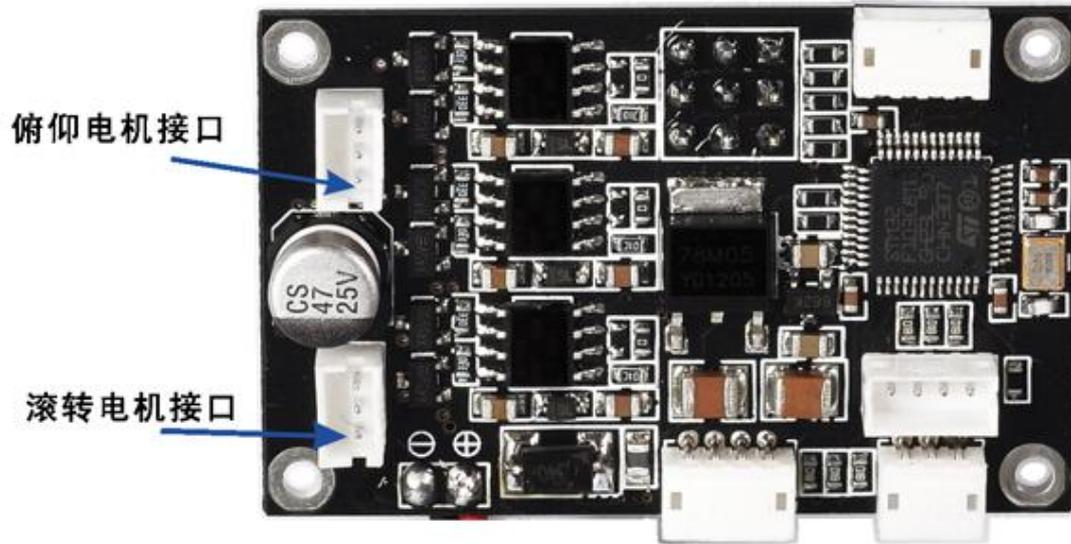
DSMX-2 : Transmitter is DX 8 etc. (22ms mode, binding by matched receiver)



7.Sensor connecto:



8. Connected with motors



2. Initial tilting angle introduction:

The initial tilting angle of T-2D default factory setting is 0 degree. If you want to change the initial tilting angle when the gimbal restart, you could modify the init tilt angle parameter in PC software, and click 'write setting to flash'.